

Λύσεις κριτηρίου 9

ΘΕΜΑ Α

A1. (α) A2. (β) A3. (γ) A4. (δ) A5. α. Σ β. Λ γ. Σ δ. Λ ε. Σ

ΘΕΜΑ Β

B1. (ii)

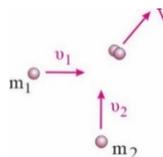
$$K_1 = K_2 = K = \frac{1}{2} m_1 v_1^2 = \frac{p_1^2}{2m_1} \Rightarrow p_1^2 = 2Km_1, p_2^2 = 2Km_2$$

$$\text{ΑΔΟ: } P_{\alpha\phi\chi} = P_{\tau\epsilon\lambda} \Rightarrow \sqrt{p_1^2 + p_2^2} = (m_1 + m_2)V \Rightarrow$$

$$2Km_1 + 2Km_2 = (m_1 + m_2)^2 V^2 \Rightarrow$$

$$K_{\tau\epsilon\lambda} = \frac{1}{2} (m_1 + m_2) V^2 = K$$

$$\pi\% = \frac{K_{\alpha\phi\chi} - K_{\tau\epsilon\lambda}}{K_{\alpha\phi\chi}} 100\% = \frac{2K - K}{2K} 100\% \Rightarrow \pi\% = 50\%$$



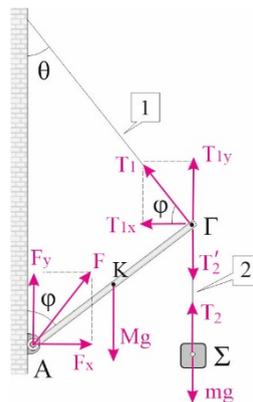
B2. (i)

$$\Sigma F_{y,\Sigma} = 0 \Rightarrow w_2 = T_2 = mg$$

$$\Sigma \tau_{(A)} = 0 \Rightarrow T_1 L = Mg \frac{L}{2} \eta \mu \phi + mg L \eta \mu \phi \Rightarrow T_1 = 0,4Mg + 0,8mg \quad (1)$$

$$\Sigma F_x = 0 \Rightarrow F_x = T_{1x}, \quad F = T_1 \Rightarrow \sqrt{F_x^2 + F_y^2} = \sqrt{T_{1x}^2 + T_{1y}^2} \Rightarrow F_y = T_{1y}$$

$$\Sigma F_y = 0 \Rightarrow F_y + T_{1y} = Mg + mg \Rightarrow 2T_1 \eta \mu \phi = Mg + mg \quad (2)$$

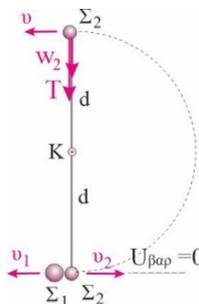


Από τις σχέσεις (1) και (2)

$$2(0,4Mg + 0,8mg) \eta \mu \phi = Mg + mg \Rightarrow 0,64Mg + 1,28mg = Mg + mg \Rightarrow 9M = 7m$$

B3. (i)

Οριακή ανακύκλωση: $T=0$, $F_k = w_2 \Rightarrow m_2 g = \frac{m_2 v^2}{d} \Rightarrow v = \sqrt{gd}$



$$\text{ΑΔΜΕ: } \frac{1}{2}m_2 v_2'^2 = \frac{1}{2}m_2 v_2^2 + \dots \Rightarrow v_2 = \sqrt{\dots}$$

$$v_2' = \frac{2m_1}{m_1 + m_2} v_0 = \frac{6m_2}{3m_2 + m_2} v_0 = \frac{3}{2} v_0, \quad L = m_2 v_2 d = \frac{m_1 v_2^2 d}{3\sqrt{5}} = \frac{1}{3} \frac{v_0^2 d}{\sqrt{5}} = \frac{1}{10} v_0^2 \sqrt{5}$$

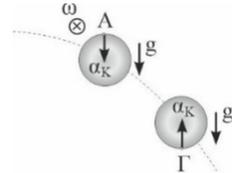
ΘΕΜΑ Γ

Γ1.

$$v_o = \omega R \Rightarrow \omega = 10 \text{ rad/s}$$

$$\alpha_{\min} = \alpha_{\Gamma} = \alpha_{\kappa} - g = \frac{v_{\gamma p}^2}{R} - g = \omega^2 R - g \Rightarrow \alpha_{\min} = 0$$

$$\alpha_{\max} = \alpha_{\Lambda} = \alpha_{\kappa} + g = \omega^2 R + g \Rightarrow \alpha_{\max} = 20 \text{ m/s}^2$$



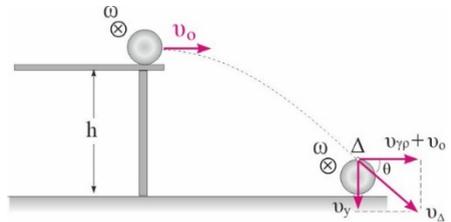
Γ2.

$$\theta = \omega t = 4 \text{ rad}, \quad N = \frac{\theta}{2\pi} = \frac{2}{\pi} \text{ στροφές}$$

$$h = \frac{1}{2}gt^2 \Rightarrow t = 0,4 \text{ s}$$

$$v_{\Delta} = \sqrt{(v_{\gamma p} + v_o)^2 + v_y^2} \Rightarrow$$

$$v_{\Delta} = \sqrt{(2\omega R)^2 + (gt)^2} \Rightarrow v_{\Delta} = 2\sqrt{5} \text{ m/s}$$



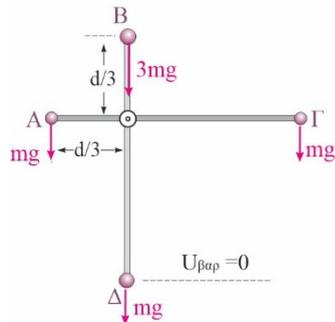
$$\varepsilon\varphi\theta = \frac{v_y}{2v_o} = 2 \Rightarrow \theta = 63^\circ$$

$$\text{Γ4. } \frac{dU_B}{dt} = -\frac{dw_B}{dt} = -\frac{mgdy}{dt} = -mgv_y = -mg^2t \Rightarrow \frac{dU_B}{dt} = -2J/s$$

ΘΕΜΑ Δ

$$\text{Δ1. } \Sigma\tau_{A(\kappa)} = mg \frac{2d}{3} - mg \frac{d}{3} = 1 \text{ Nm}, \quad \Sigma\tau_{B(\kappa)} = 0$$

Δ2. ΑΔΜΕ:



$$g \frac{2d}{3} + g \frac{2d}{3} = gd + \frac{1}{2} \left(\omega \frac{d}{3} \right)^2 + \frac{1}{2} \left(\omega \frac{2d}{3} \right)^2 \Rightarrow$$

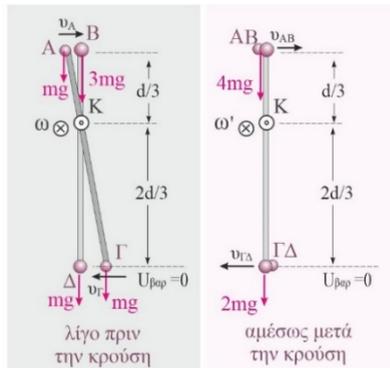
$$mg \frac{2d}{3} + mg \frac{2d}{3} = mgd + \frac{1}{2} m v_A^2 + \frac{1}{2} m v_\Gamma^2 \Rightarrow \omega = 2 \text{ rad/s} \quad , \quad v_\Gamma = \omega \frac{2d}{3} = 4 \text{ m/s}$$

Δ3. ΑΔΣ:

$$m v_A \frac{d}{3} + m v_\Gamma \frac{2d}{3} = 4 m v_{AB} \frac{d}{3} + 2 m v_{\Gamma\Delta} \frac{2d}{3} \Rightarrow$$

$$m \omega \left(\frac{d}{3} \right)^2 + m \omega \left(\frac{2d}{3} \right)^2 = 4 m \omega \left(\frac{d}{3} \right)^2 + \omega \left(\frac{2d}{3} \right)^2 \Rightarrow$$

$$\omega' = \frac{5}{12} \omega = \frac{5}{6} \text{ rad/s}$$



Δ **4**

$$Q = \frac{1}{2} m v_A^2 + \frac{1}{2} m v_\Gamma^2 - \left[\frac{1}{2} 4 m v_{AB}^2 + \frac{1}{2} 2 m v_{\Gamma\Delta}^2 \right] \Rightarrow$$

$$Q = \frac{1}{2} m \left(\omega \frac{d}{3} \right)^2 + \frac{1}{2} m \left(\omega \frac{2d}{3} \right)^2 - \frac{1}{2} 4 m \left(\omega \frac{d}{3} \right)^2 - \frac{1}{2} \left(\omega \frac{2d}{3} \right)^2 \Rightarrow Q = \frac{7}{12} m \omega^2 d^2$$

Δ5. $t = \frac{T}{2} = \frac{2\pi}{2\omega} = 1,2\pi \text{ s}$