

Λύσεις κριτηρίου 12

ΘΕΜΑ Α

A1. (α) A2. (γ) A3. (δ) A4. (α) A5. α. Λ β. Σ γ. Σ δ. Λ ε. Σ

ΘΕΜΑ Β

B1. (i)

$$T_1 = T_2 \Rightarrow 2\pi\sqrt{\frac{m_1}{k_1}} = 2\pi\sqrt{\frac{m_2}{k_2}} \Rightarrow \frac{m_1}{k_1} = \frac{m_2}{k_2} \quad (1)$$

$$\text{Π.θ.λ.: } \Sigma F_2 = 0 \Rightarrow T = m_2 g \quad (2)$$

$$\text{Π.θ.λ.: } \Sigma F_1 = 0 \Rightarrow T + m_1 g = F_{\epsilon\lambda} = k_1 x_1 \quad (3)$$

Από (2) και (3)

$$(m_1 + m_2)g = k_1 x_1 \quad (4)$$

$$\text{Ν.θ.λ.: } \Sigma F_2 = 0 \Rightarrow m_2 g = F_{\epsilon\lambda} = k_2 x_2$$

$$\Rightarrow x_2 = A_2 = \frac{m_2 g}{k_2}$$

$$\text{Ν.θ.λ.: } \Sigma F_1 = 0 \Rightarrow$$

$$m_1 g = F_{\epsilon\lambda} = k_1 (x_1 - A_1) = k_1 x_1 - k_1 A_1 \Rightarrow$$

$$m_1 g = (m_1 + m_2)g - k_1 A_1 \Rightarrow A_1 = \frac{m_2 g}{k_1}$$

$$A_1 = A_2 \Rightarrow \frac{m_2 g}{k_1} = \frac{m_2 g}{k_2} \Rightarrow k_1 = k_2 \xrightarrow{(1)} m_1 = m_2$$

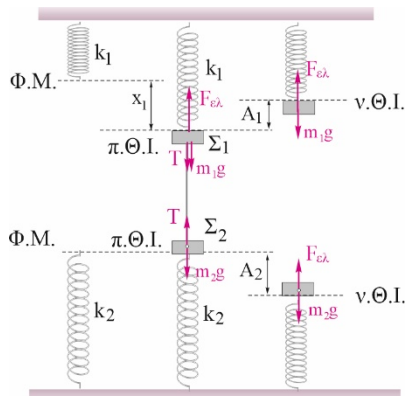
B2. (i)

$$W_{F_{\epsilon\lambda}} = -\Delta U = U_B - U_r = \frac{1}{2} D x_B^2 - \frac{1}{2} D x_r^2 \quad (1)$$

$$\text{ΑΔΕΤ: } E = K_B + U_B \Rightarrow \frac{1}{2} D A^2 = K_B + \frac{1}{2} D x_B^2 \Rightarrow K_B = \frac{1}{2} D (A^2 - x_B^2)$$

$$\text{Ομοίως } K_r = \frac{1}{2} D (A^2 - x_r^2)$$

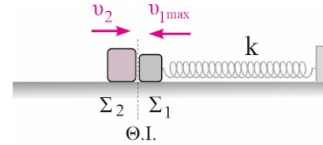
Ομοίως



$$\frac{K_B}{K_\Gamma} = \frac{\frac{1}{2}D(A^2 - x_B^2)}{\frac{1}{2}D(A^2 - x_\Gamma^2)} \Rightarrow \frac{A^2 - 3x_\Gamma^2}{A^2 - x_\Gamma^2} = \frac{1}{3} \Rightarrow x_\Gamma = \pm \frac{A}{2} \quad \text{και} \quad x_B = \pm \frac{A\sqrt{3}}{2}$$

Από (1)
$$W_{\text{εξ}} = \frac{1}{2}D \frac{3A^2}{4} - \frac{1}{2}D \frac{A^2}{4} \Rightarrow W_{\text{εξ}} = \frac{E}{2}$$

B3. (iii)



$$\alpha_{1,\max} = \alpha_{2,\max} \Rightarrow \omega_1^2 A_1 = \omega_2^2 A_2 \Rightarrow$$

$$\frac{k}{m_1} A_1 = \frac{k}{m_1 + m_2} A_2 \Rightarrow A_2 = 4A_1$$

$$\Delta\Delta O: P_{\text{αρχ}} = P_{\text{τελ}} \Rightarrow m_2 v_2 - m_1 v_{1,\max} = (m_1 + m_2) v_{\max} \Rightarrow$$

$$3m v_2 - m \omega_1 A_1 = 4m \omega_2 A_2 \Rightarrow 3m v_2 - m \sqrt{\frac{k}{m_1}} A_1 = 4m \sqrt{\frac{k}{m_1 + m_2}} A_2 \Rightarrow v_2 = 3A_1 \sqrt{\frac{k}{m_1}}$$

ΘΕΜΑ Γ

Γ1.

$$\Delta\Delta E T: E = K + U \Rightarrow K = E - \frac{1}{2}Dx^2 = 1 - 25x^2 \Rightarrow D = 50 \text{ N/m} \quad \text{και} \quad E = 1 \text{ J}$$

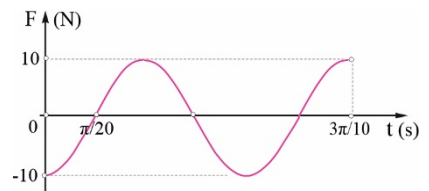
$$T = 2\pi \sqrt{\frac{m}{D}} \Rightarrow T = \frac{\pi}{5} \text{ s}$$

Γ2.
$$\omega = \frac{2\pi}{T} = 10 \text{ rad/s}$$

$$E = \frac{1}{2}DA^2 \Rightarrow A = 0,2 \text{ m}$$

Για $t=0$ είναι $\chi=A$,

$$x = A\eta\mu(\omega t + \phi_0) \Rightarrow A = A\eta\mu\phi_0 \Rightarrow \phi_0 = \frac{\pi}{2} \text{ rad}$$



$$F = -Dx = -DA\eta\mu\left(\omega t + \frac{\pi}{2}\right) = -10\eta\mu\left(10t + \frac{\pi}{2}\right) \quad (\text{S.I.})$$

$$\Delta t = \frac{3\pi}{10} \text{s} = 1,5\text{T}$$

Γ3.

$$v_1 = \omega A \sigma\upsilon\nu\left(\omega t_1 + \frac{\pi}{2}\right) = 2\sigma\upsilon\nu\left(10t_1 + \frac{\pi}{2}\right) = -1\text{m/s}$$

$$v_2 = \omega A \sigma\upsilon\nu\left(\omega t_2 + \frac{\pi}{2}\right) = 2\sigma\upsilon\nu\sigma\upsilon\nu\left(10t_2 + \frac{\pi}{2}\right) = 2\text{m/s}$$

$$\Delta p = p_2 - p_1 = mv_2 - mv_1 \Rightarrow \Delta p = 1,5\text{kgm/s}$$

Γ4. $x_1 = A = 0,2\text{m}$, $x_2 = A\eta\mu\left(\omega t_2 + \frac{\pi}{2}\right) = 0,2\eta\mu\left(10t_1 + \frac{\pi}{2}\right) = 0$

$$t_2 = \frac{7\pi}{20} \text{s} = \frac{7}{4} \text{T} , \quad d = 7A = 1,4\text{m}$$

Γ5. $x_1 = A\eta\mu\left(\omega t_1 + \frac{\pi}{2}\right) = 0,2\eta\mu\left(10t_1 + \frac{\pi}{2}\right) = -0,1\sqrt{3}\text{m}$

$$\frac{dK}{dt} = \frac{W_{F_{\text{ext}}}}{\Delta t} = F_{\text{ext}}v_1 = -Dx_1v_1 \Rightarrow \frac{dK}{dt} = -5\sqrt{3}\text{J/s}$$

ΘΕΜΑ Δ

Δ1.

$$\text{Π.}\theta.\text{.} : \Sigma F = 0 \Rightarrow N + mg = F_{\epsilon\lambda} = 10\text{N}$$

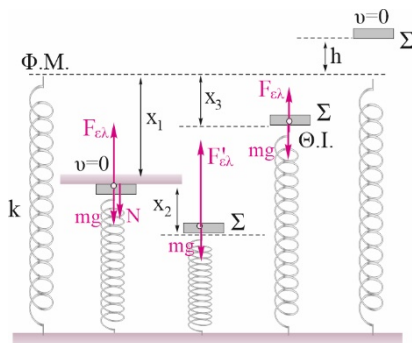
$$F_{\epsilon\lambda} = kx_1 \Rightarrow x_1 = 0,1\text{m}$$

$$F_{\epsilon\lambda} = \dots = (x_1 + x_2) \Rightarrow x_2 = \dots$$

$$\text{Ν.}\theta.\text{.} : \Sigma F = 0 \Rightarrow mg = F_{\epsilon\lambda} = kx_3 \Rightarrow$$

$$x_3 = \frac{mg}{k} = 0,05\text{m}$$

$$A = x_1 + x_2 - x_3 \Rightarrow A = 0,1\text{m}$$



$$\omega = \sqrt{\frac{k}{m}} \Rightarrow \omega = 10\sqrt{2} \text{ rad/s}$$

Δ2.

Για $t=0$ είναι $x=A$, άρα

$$x = A\eta\mu(\omega t + \varphi_0) \Rightarrow A = A\eta\mu\varphi_0 \Rightarrow \varphi_0 = \frac{\pi}{2} \text{ rad}$$

$$x = A\eta\mu\left(\omega t + \frac{\pi}{2}\right) = 0,1\eta\mu\left(10\sqrt{2}t + \frac{\pi}{2}\right) \Rightarrow x_1 - x_3 = 0,05 = 0,1\eta\mu\left(10\sqrt{2}t + \frac{\pi}{2}\right) \Rightarrow$$

$$\eta\mu\left(10\sqrt{2}t + \frac{\pi}{2}\right) = 0,5 = \eta\mu\frac{\pi}{6} \xrightarrow{v(0)} 10\sqrt{2}t + \frac{\pi}{2} = \frac{5\pi}{6} \Rightarrow t = \frac{\pi\sqrt{2}}{60} \text{ s}$$

Δ3.

$$\text{ΑΔΕΤ: } \frac{1}{2}kA^2 = \frac{1}{2}mv^2 + \frac{1}{2}k(x_1 - x_3)^2 \Rightarrow v = \pm\sqrt{\frac{3}{2}} \text{ m/s} \Rightarrow v = -\sqrt{\frac{3}{2}} \text{ m/s}$$

$$\frac{dU_{\varepsilon\lambda}}{dt} = -\frac{W_{F_{\varepsilon\lambda}}}{\Delta t} = -F_{\varepsilon\lambda}v = -(-kx_1)v \Rightarrow \frac{dU_{\varepsilon\lambda}}{dt} = -10\sqrt{\frac{3}{2}} \text{ J/s}$$

Δ4. Η επαφή του σώματος από το ελατήριο θα χαθεί όταν αυτό φτάσει στο φυσικό μήκος του.

$$\text{ΑΔΕΤ: } \frac{1}{2}kA^2 = \frac{1}{2}mv_2^2 + \frac{1}{2}kx_3^2 \Rightarrow v_2 = \pm\sqrt{\frac{3}{2}} \text{ m/s}$$

$$\text{ΑΔΜΕ: } K_{\text{αρχ}} = U_{\text{τελ}} \Rightarrow \frac{1}{2}mv_2^2 = mgh \Rightarrow h = 0,075 \text{ m}$$

$$H = x_1 + h = 0,175 \text{ m}$$