

Λύσεις κριτηρίου 7

ΘΕΜΑ Α

A1. (δ) A2. (α) A3. (β) A4. (γ) A5. α. Λ β. Λ γ. Σ δ. Σ ε. Σ

ΘΕΜΑ Β

B1. (iii)

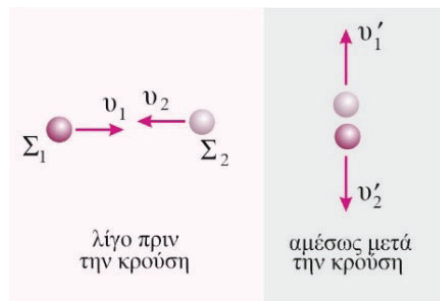
$$K_2 = 3K_1 \Rightarrow \frac{1}{2}m_2v_2^2 = 3\frac{1}{2}m_1v_1^2 \quad (1)$$

$$\Delta\Delta O(x): P_{\alpha\rho\chi,x} = P_{\tau\epsilon\lambda,x} \Rightarrow m_1v_1 - m_2v_2 = 0 \quad (2)$$

Από (1) και (2) προκύπτει:

$$v_2 = 3v_1 \quad \text{και} \quad m_1 = 3m_2$$

$$\Delta\Delta O(y): P_{\alpha\rho\chi,y} = P_{\tau\epsilon\lambda,y} \Rightarrow 0 = m_1v_1' - m_2v_2' \Rightarrow v_2' = 3v_1'$$

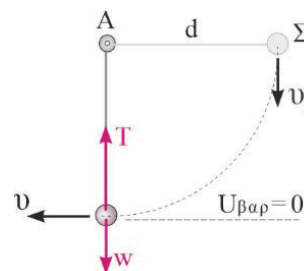


B2. (ii)

$$F_k = T - w = \frac{mv^2}{d} \Rightarrow 4mg - mg = \frac{mv^2}{d} \Rightarrow v = \sqrt{3gd}$$

$$\Delta\Delta ME: \frac{1}{2}mv_0^2 + mgd = \frac{1}{2}mv^2 \Rightarrow v_0 = \sqrt{gd}$$

$$\frac{L'}{L} = \frac{mvd}{mv_0d} = \frac{v}{v_0} \Rightarrow L' = L\sqrt{3}$$



B3. (i)

$$L_2 = 2L_1 \Rightarrow m_2|v_2|d = 2m_1|v_1|d \Rightarrow |v_2| = |v_1|$$

$$v_1' = \frac{m_1 - m_2}{m_1 + m_2}v_1 + \frac{2m_2}{m_1 + m_2}v_2 \Rightarrow$$

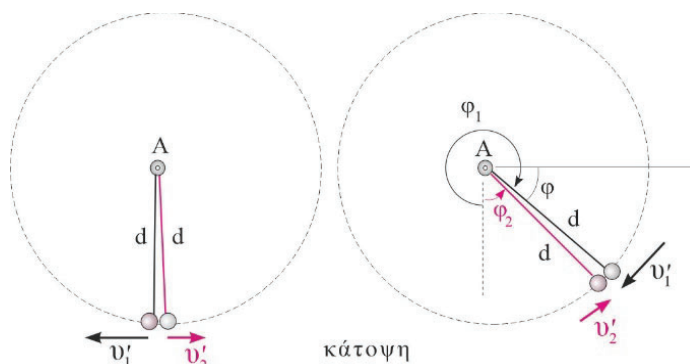
$$v_1' = -\frac{5}{3}v_1 \quad (v_2 = -v_1)$$

$$v_2' = \frac{2m_1}{m_1 + m_2}v_1 + \frac{m_2 - m_1}{m_1 + m_2}v_2 \Rightarrow$$

$$v_2' = \frac{1}{3}v_1$$

$$\varphi_1 + \varphi_2 = 2\pi \Rightarrow \omega_1 t + \omega_2 t = \frac{|v_1'|}{d}t + \frac{v_2'}{d}t = 2\pi \Rightarrow t = \frac{\pi d}{v_1}, \quad \varphi_2 = \omega_2 t = \frac{v_2'}{d}t = \frac{v_1}{3d} \frac{\pi d}{v_1} \Rightarrow \varphi_2 = \frac{\pi}{3} \text{ rad}$$

$$\varphi = \frac{\pi}{2} - \varphi_2 = \frac{\pi}{6} \Rightarrow \varphi = 30^\circ$$



ΘΕΜΑ Γ

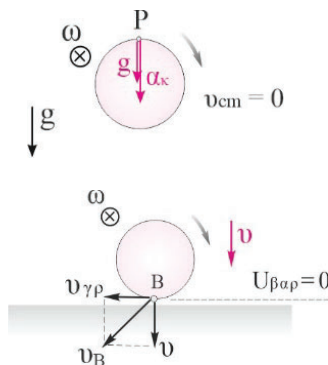
Γ1. $y = v_0 t - \frac{1}{2} g t^2 = 0 \Rightarrow t = \frac{2v_0}{g} = 2s, \theta = \omega t = 80\text{rad}, N = \frac{\theta}{2\pi} = \frac{40}{\pi}$ στροφορές

Γ2. $\alpha_p = \alpha_k + g = \omega^2 r + g = 170\text{m/s}^2$

Γ3. ΑΔΜΕ: $\frac{1}{2} m v_0^2 + 0 = \frac{1}{2} m v^2 + 0 \Rightarrow v = v_0 = 10\text{m/s}$

$v_B = \sqrt{v_{\gamma\rho}^2 + v^2} = \sqrt{(\omega r)^2 + v^2} \Rightarrow v_B = \sqrt{116}\text{m/s}$

$\epsilon\varphi\theta = \frac{v}{v_{\gamma\rho}} = 2,5$

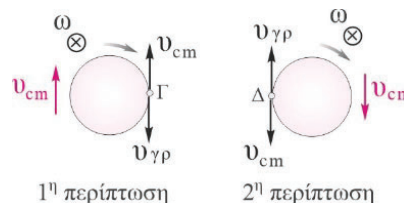


Γ4. 1^η περίπτωση:

$v_{\Gamma} = v_{cm} - v_{\gamma\rho} = 0 \Rightarrow v_0 - g t_1 = \omega r \Rightarrow t_1 = 0,6s$

2^η περίπτωση:

$v_{\Delta} = |v_{cm}| - v_{\gamma\rho} = 0 \Rightarrow |v_0 - g t_2| = g t_2 - v_0 = \omega r \Rightarrow t_2 = 1,4s$



ΘΕΜΑ Δ

Δ1. $\Sigma\tau_{(B)} = 0 \Rightarrow Mg \frac{L}{2} = N_{\Gamma} \frac{2L}{3} \Rightarrow M = 4\text{kg}$

$\Sigma F = 0 \Rightarrow N_B + N_{\Gamma} = Mg + m_1 g \Rightarrow m_1 = 3,9\text{kg}$

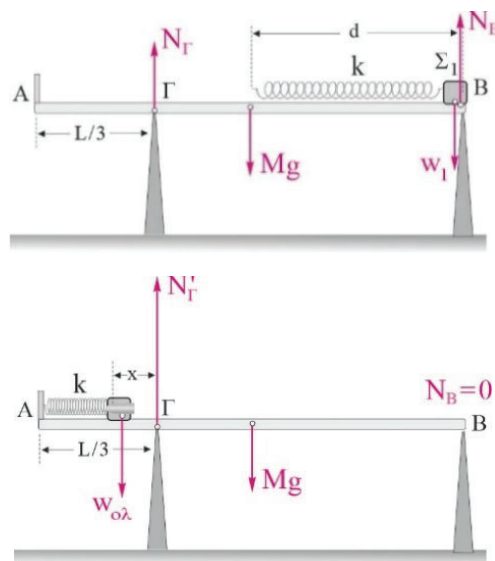
Δ2. $\Sigma\tau_{(\Gamma)} = 0 \Rightarrow Mg \frac{L}{6} = (m_1 + m_2) g x \Rightarrow$

$x = \frac{L}{6} = 0,5\text{m}$

αριστερά του σημείου Γ.

$T = \mu N = \mu(m_1 + m_2)g = 10\text{N}$

ΘΜΚΕ: $0 - \frac{1}{2}(m_1 + m_2)V^2 = -T(\frac{2L}{3} + x) - \frac{1}{2}k(\frac{L}{2} - \frac{L}{3} + x)^2 \Rightarrow V = 5\text{m/s}$



$$\Delta 3. \text{ ΑΔΟ: } m_2 v_0 = (m_1 + m_2) V \Rightarrow v_0 = 200 \text{ m/s}$$

$$Q_1 = \frac{1}{2} m_2 v_0^2 - \frac{1}{2} m_{12} V^2 = 1950 \text{ J} \quad , \quad Q_2 = |W_T| = T \left(\frac{2L}{3} + x \right) \Rightarrow Q_2 = 25 \text{ J}$$

$$Q_{\text{ολ}} = Q_1 + Q_2 = 1975 \text{ J} \quad \text{ή} \quad Q_{\text{ολ}} = E_{\text{αρχ}} - E_{\text{τελ}} = \frac{1}{2} m_2 v_0^2 - \frac{1}{2} k \left(\frac{L}{3} \right)^2 \Rightarrow Q_{\text{ολ}} = 1975 \text{ J}$$

$$\Delta 4. \text{ ΘΜΚΕ: } \frac{1}{2} (m_1 + m_2) v^2 - \frac{1}{2} (m_1 + m_2) V^2 = -T \frac{L}{2} \Rightarrow v = \sqrt{17,5} \text{ m/s}$$

$$\frac{dQ}{dt} = \frac{d|W_T|}{\Delta t} = \frac{T dx}{dt} = T v \Rightarrow \frac{dQ}{dt} = 42 \text{ J/s}$$